Simple, strict, proper, happy: A study of reachability in temporal graphs

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A temporal graph is a graph that changes with time. $\mathcal{G} = (V, E, \lambda)$ with $\lambda : E \to 2^{\tau}$. *n* vertices, *m* edges, τ the lifetime.



Reachability in Temporal Graphs

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- journey from b to e but not from e to b
- ullet $\mathcal G$ is not temporally connected

Temporal Reachability

u can reach v if there is a journey from u to v.

Temporal connectivity

Every vertex can reach the others.

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Both simple and proper.









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"Happiness"

Both simple and proper.









More Inportant than it seems!







- \mathcal{G}_2 is a non-strict min-labelled spanner
- $\bullet \ \mathcal{G}_3$ is a strict min-labelled spanner
- $\bullet \ {\cal G}_4$ is a strict min-edge spanner



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- $\bullet \ \mathcal{G}_5$ is a strict min spanner of itself

Outline



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What concept captures expressitivy?

How to compare expressitivy ?

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Reachability graph

A directed graph H = (V, E') s.t. $(u, v) \in E'$ iff u can reach v in the original graph.

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Reachability graph expressitivy

Can a given reachability graph be obtained from a given setting?

Separating the settings

Outline



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From "strict and simple" to "non-strict"









The "simple and strict" setting cannot be realized in the "non-strict" setting.







Transformations between settings





Goal : Turn a graph from "non-strict" to "strict" with the same reachability.

Saturation method

 $\mathcal{G} \to \mathcal{H}$ such that there is a contact $(\{u, v\}, t)$ in \mathcal{H} if and only if $\{u, v\}$ are connected at time t in \mathcal{G} .

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 \exists Strict (u, v)-journey in \mathcal{H} if and only if \exists non-strict (u, v)-journey in \mathcal{G}





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Turn $\mathcal G$ into $\mathcal H$ such that the journeys use the same support (same sequence of edges).

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Lemma

 ${\mathcal G}$ and ${\mathcal H}$ have the same reachability.

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Нарру















Observations

- Happy is the least expressive
- Strict is the most expressive

Conclusion


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Thanks for your attention !

