

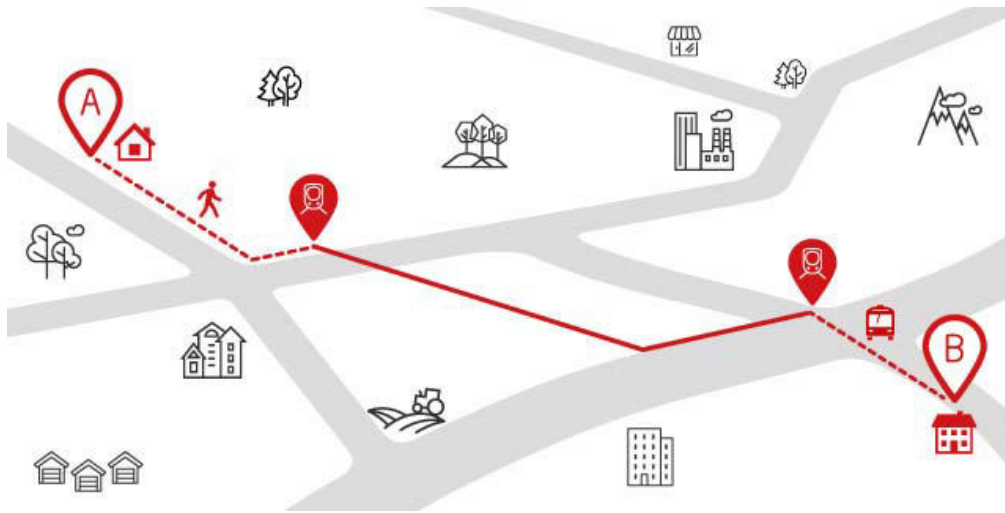
Multimodal Dynamic Journey Planning



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Journey Planning



Zeit / Time / Temps		Über / Via	
18:29	ICE 1613	Donauw. - Augsburg	Berlin
18:31	ICE 229	Regensburg - Passau - Linz Hbf	Stuttg
18:33	ICE 1502	Saalfeld (S) - Jena - Leipzig	Neust
18:35	RE 19924	Ansbach - Crailsheim - Backnang	Lauf (
18:36	RE 3581	Neukirchen (b.S-R) - Weiden	Münch
18:37	S1	Rothenbach (P)	Schwe
18:38	RB 30291	Schwabach - Roth - Treuchtlingen	Allers
18:39	RE 4792	Fürth - Erlangen - Bamberg	Dresd
18:40	RB 35979	Fürth - Erlangen - Bamberg	Lichte
18:42	IRE 3097	Kirchentailbach - Hof - Plauen - Chemnitz	Roth
18:45	RB 34078	Fürth - Erlangen - Bamberg	Altdo
	S3	Schwabach	Schw
		kenstadion - Feucht	Mark
		kirchen (b.S-R)	

Journey Planners

compute best journeys in public (scheduled-based) transport networks

Optimization problems (also in a *multimodal* setting)

- **Earliest Arrival Problem (EAP)**: find the best journey from A to B that minimizes the arrival time at B , when departing from A after time t
- **Minimum Number of Transfers Problem (MNTP)**: find the best journey from A to B that minimizes the number of vehicle transfers, when departing from A after time t

Journey Planning



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Journey Planners

compute best journeys in public (scheduled-based) transport networks

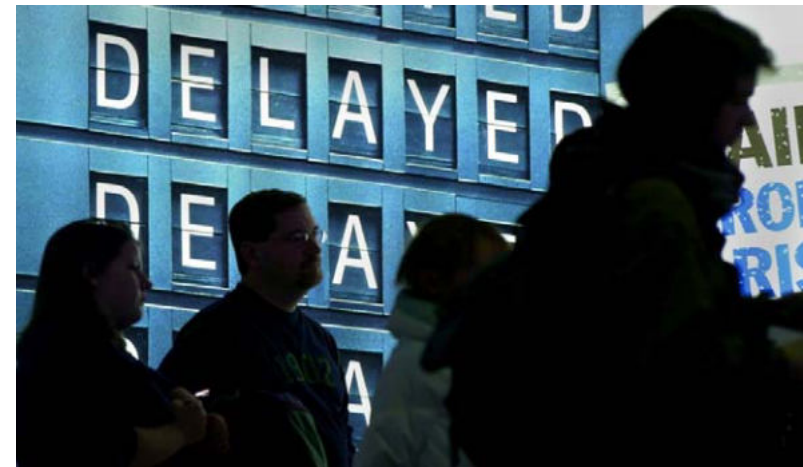
Optimization problems (also in a *multimodal* setting)

- **Multicriteria Problem (MP)**: find the optimal Pareto set of journeys from A to B minimizing the EA and MNT criteria
- **Profile query Problem (PP)**: find the set of the earliest arrival journeys from A to B , departing from A within a given departure time interval $I=[t_1, t_2]$

Journey Planning

Challenges in scheduled-based journey planning:

- Inherent time-dependent component & **transfer time among vehicles**: complex modeling
- Accommodate **multimodality**:
 - Scheduled-based transport across multiple modes (eg train, bus, tram)
 - Unrestricted/Restricted (wrt departing time) traveling (walking, EVs)
- Accommodate **delays** of scheduled vehicles so that timetable information is correctly and efficiently updated
- **High query demand**: real-time answering (also in mobile devices)



State-of-the-Art

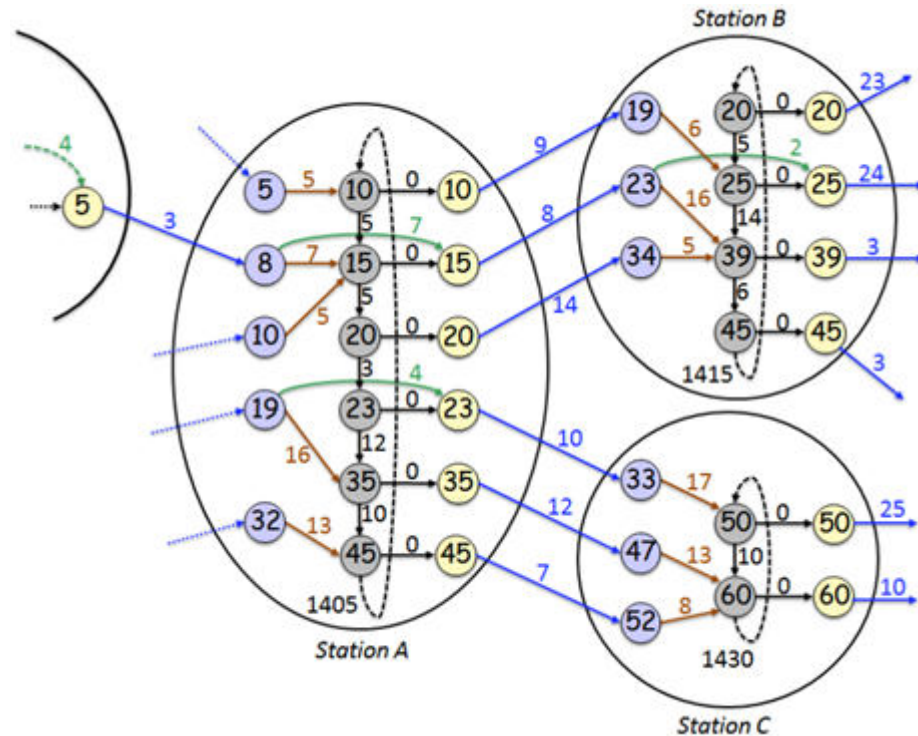
- **Journey Planning (public transport)**
 - **Array-based approaches**
 - RAPTOR [Dibbelt et al 2012]
 - Connection Scan Algorithm [Dibbelt et al 2013]
 - Public Transit Labeling [Dibbelt et al 2015]
 - Trip-based public transit routing [Witt 2015]
 - **Graph-based approaches**
 - Time-expanded (TE) realistic model [Pyrga et al 2004 & 2008]
 - Reduced TE (TE-Red) [Pyrga et al 2008; Cionini et al 2014 & 2017]
- **Dynamic (unimodal) journey planning**
 - Dynamic TE-Red [Cionini et al 2014 & 2017]
 - Dynamic Timetable Model (DTM) [Cionini et al 2014 & 2017]
- **Multimodal Journey Planning**
 - McRAPTOR [Delling et al 2013; Dibbelt 2016]
 - **Questions**
 - *Can graph-based approaches be competitive to SotA ?*
 - *Dynamization ?*

Main Contributions

- **Multimodal Dynamic Journey Planner**
 - New model: *Multimodal DTM* (extension of Dynamic Timetable Model)
 - Efficient **core engine** for real-time response and update requirements
 - Comparative experimental study in large metropolitan networks (London, Berlin)
 - **Multimodal EAP, multicriteria & profile queries:**
competitive (with SotA) even in the case of unlimited/limited walking or Evs
 - Limited Walking **Query**: < 16 msec
 - **Update**: < 0.17 msec

Time-Expanded Realistic Model

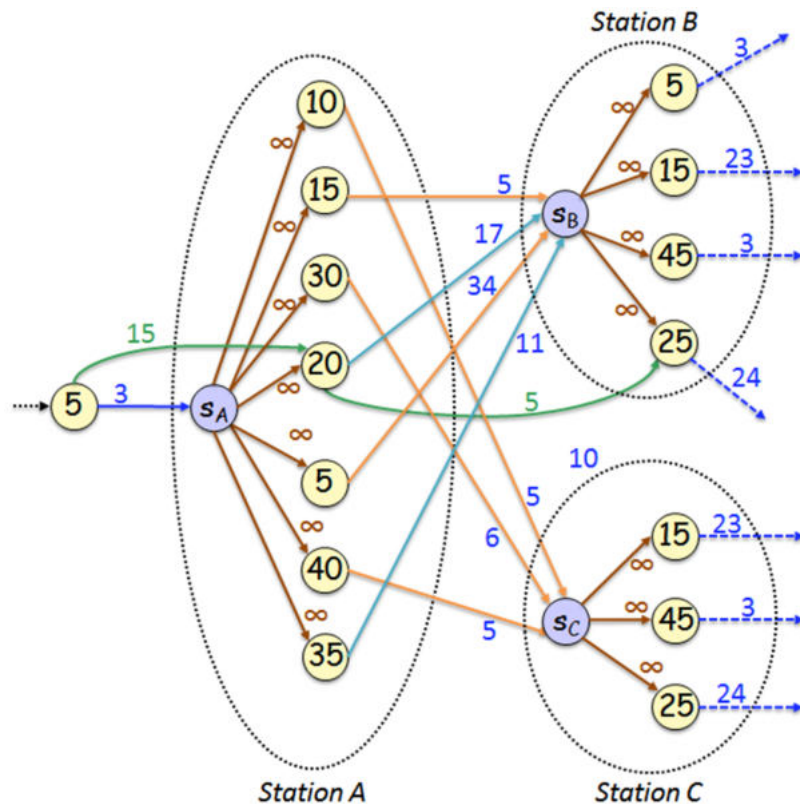
[Pyrga, Schulz, Wagner & Z, 2004 & 2008]



- Node **blue**/grey/**yellow** \equiv arrival/transfer/**departure**
- Arc **blue**/**green**/**black** \equiv connection/arrival-departure/transfer-x
- C : connections; $n = \#$ nodes; $m = \#$ arcs;
- **Space:** $O(|C|)$ ($n = 3|C|$; $4|C| \leq m \leq 5|C|$)

Dynamic Timetable Model (DTM)

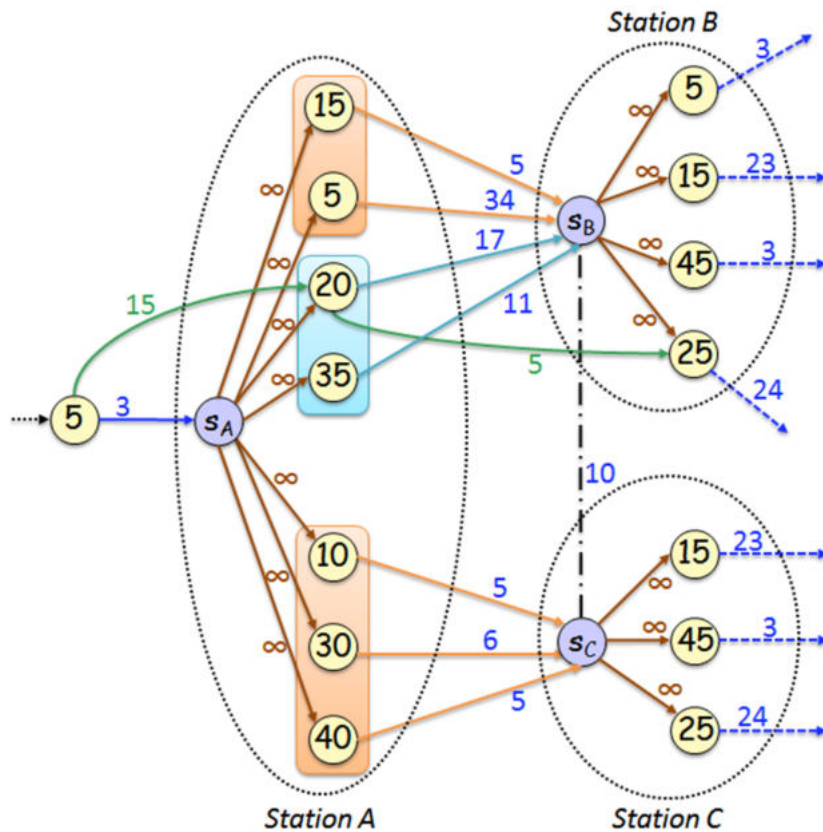
[Cionini, D'Angelo, Emidio, Frigioni, Giannakopoulou, Paraskevopoulos & Z, 2014 & 2017]



- node **blue**/**yellow** \equiv **switch**/**departure**
- arc **brown**/**green**/**other** \equiv
switch/**vehicle**/**connection**
- **Space:** $O(|C|)$ ($n = |B| + |C|$; $m \leq 3|C|$)
 B : stations; C : connections; $n = \#$ nodes;
 $m = \#$ arcs;

- The departure nodes are ordered by **increasing arrival time at the next station**

New: Multimodal DTM



- node **blue**/**yellow** \equiv **switch**/**departure** (ordered by arrival time)
- arc **brown**/**green**/**other** \equiv **switch**/**vehicle**/**connection**
- connection arc **dotted** / **solid** \equiv **unrestricted-departure** / **restricted-departure**
- grouping **blue** / **orange** \equiv **train** / **bus** travelling
- **Space**: $O(|C|)$ ($n = |B| + |C|$; $m \leq 3|C|$)

- **Grouping of Departure nodes**

- Γ_1 (**primary**): departure nodes with the same **head switch node**
- Γ_2 (**secondary** grouping within Γ_1): departure nodes of the same **transport mode**
- **Departure nodes within Γ_2** are ordered by **increasing arrival time at the next station**

Multimodal DTM - Query

Unicriteria Query Algorithm (modified Dijkstra)

- **Start** at s_S at departure station S.
- **Stop** when s_T at arrival station T is settled.
- **If** switch node settled **then** *set switch arc weights:* departure event reachable in current time period \equiv dep. time $>$ current time + transfer time
- **Skip** unselected transportation means and past departures

Multicriteria Query Algorithm (modified multicriteria Dijkstra)

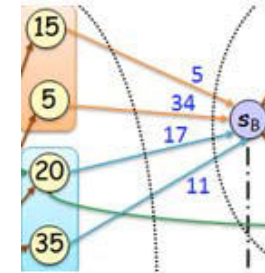
- Criteria: EA & MNT
- Transfer weight: 1 for all switch edges; 0, otherwise

Restriction: Non-dominating EA & MNT journeys with arrival time $< P \cdot A_{\min}$

A_{\min} : minimum arrival time, P: threshold

Heuristic Improvements

- Pruning (EAX)
- Exploiting station topology
- ALT



Earliest Arrival Index (EAX)

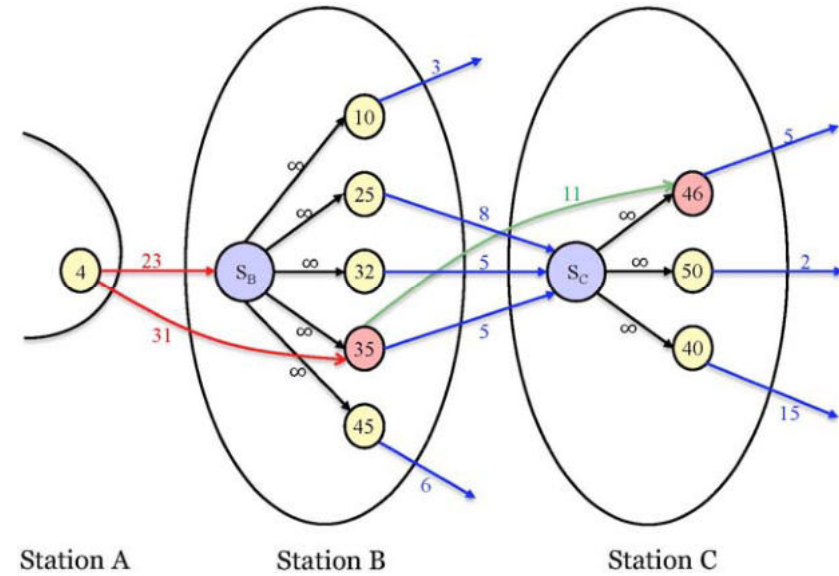
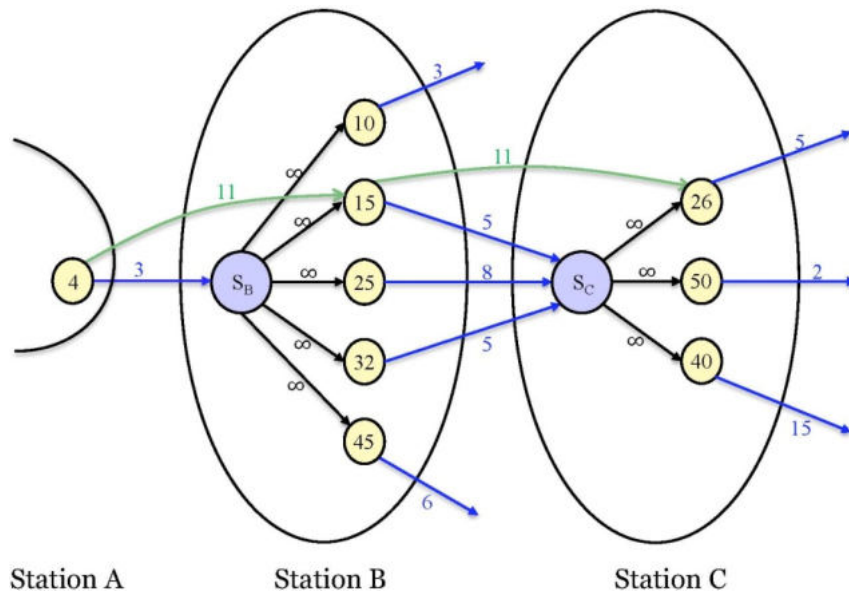
Partially encodes the departure time ordering (efficient search on valid non-past routes) and the arrival time ordering (efficient search on optimal routes)

For each consecutive pair (d_i, d_{i+1}) in EAX: d_{i+1} has greater departure and arrival time than d_i .

depNode	depTime	arrTime
d15	15	20
d20	20	37
d35	35	46

e.g. if arrival/starting time is 25 ($>$ 20)
 \Rightarrow search for valid and optimal paths after d20

Multimodal DTM - Update



∀ Affected station

• Update

- Arc weights of arrival-departure arcs
- Time associated with departure nodes
- Repair the node arrival-time ordering within the affected groups

- Delay: 20 mins
- **Red**: updated arc weights, time associated with affected **departure** nodes
- Topology does **NOT** change

MDTM - Experimental Setup

			TE		TE (red)		DTM		MDTM	
City	Stations	Conn.	V	E	V	E	V	E	V	E
Berlin	12,838	4,322,549	12,967,647	21,612,745	8,645,098	17,024,138	4,335,387	12,701,695	4,335,387	12,708,568
London	20,843	14,064,967	42,194,901	70,324,835	28,129,934	55,758,468	14,085,810	41,837,355	14,085,810	41,856,048

	Berlin	London
Bus	76%	98%
Train	15%	2%
Tram	9%	

	Berlin		London	
	V	E	V	E
road		39		60
pedestrian L-Walk		2,381		37,226
pedestrian U-Walk	932,108	1,059,556	1,520,056	1,653,052

CPU: Intel Quad-core i5-2500K 3.30GHz

RAM: 32GB

Data: GTFS (Public transport timetables)

OSM (road and pedestrian networks)

- **Driving-paths:** free flow speed travelling between stops via shared EVs.

10 EV-stations, driving travel-time $\leq 1h$

- **Foot-paths:** walking speed 1m/s
 - Limited walking (L-Walk):** Walk paths between stops with travel time ≤ 10 mins
 - Unlimited walking (U-Walk):** The full pedestrian network is embedded and each switch node is connected with the nearest pedestrian node

MDTM - Experimental Evaluation

	Algorithm	MC	Travel Modes				Query [ms]	
			Public Transit	Walk	EV/Car	Cycle	L-Walk	U-Walk
Berlin	TE-QH-ALT [1]		●				6.28	
	DTM-QH-ALT [1]		●				11.66	
	MDTM-QH-ALT		●				5.71	
	MDTM-QH-ALT		●	●	●		8.15	103.46
London	TE-QH-ALT [1]		●				5.09	
	DTM-QH-ALT [1]		●				9.81	
	MDTM-QH-ALT		●				4.01	
	MDTM-QH-ALT		●	●	●		6.02	107.93
	McMDTM-QH-ALT-1.0	●	●	●	●		6.22	215.27
	McMDTM-QH-ALT-1.2	●	●	●	●		15.40	360.56
	MCR-ht [2]	●	●			●		361.23
	MR- ∞ -t10 [2]	●	●			●	21.47	
	PfMDTM-QH-ALT [2h]		●	●	●			2,150.2
	PfMDTM-QH-ALT [24h]		●	●	●			29,365.4

MDTM - Experimental Evaluation

	Algorithm	Update [μ s]
Berlin	TE-UH	249.3
	DTM-U	85.7
	MDTM-U	87.2
London	TE-UH	484.6
	DTM-U	148.1
	MDTM-U	163.1

random [1, 360] mins delays in 10K
randomly chosen elementary connections

Conclusion & Future Work

Multimodal Dynamic Journey Planner

- Real-time query responses for single and multicriteria queries
- Accommodation of walking and EV scenarios
- Accommodation of delays

Future work

- Investigate further realistic settings
- Mobile app

Thank You. Questions ?