

On Separators in Temporal Graphs

Hendrik Molter



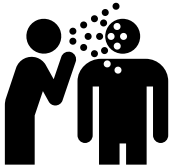
Algorithmics and Computational Complexity,
TU Berlin, Germany

Algorithmic Aspects of Temporal Graphs,
Satellite Workshop of ICALP 2018, Prague

Based on joint work with Till Fluschnik, Rolf Niedermeier and Philipp Zschoche.

Introduction

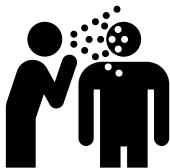
Motivation: Separators



- Disease Spreading

Introduction

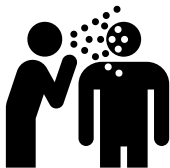
Motivation: Separators



- Disease Spreading
- Rumor Spreading

Introduction

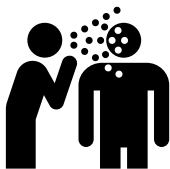
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- Disease Spreading
- Rumor Spreading
- Physical Proximity Networks

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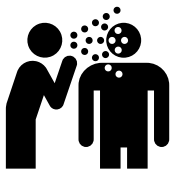


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- Robustness of Connections

Introduction

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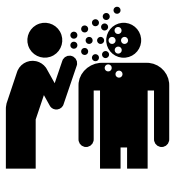


- Disease Spreading
- Rumor Spreading
- Physical Proximity Networks

- Robustness of Connections
- Traffic Networks

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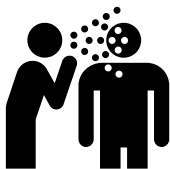
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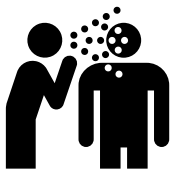
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- Malware Spreading

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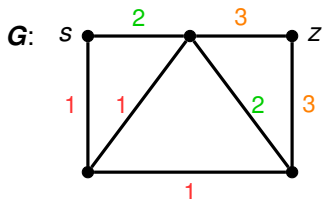
- Malware Spreading
- Rumor Spreading
- Social Networks / Computer Networks

Temporal Graph

A **temporal graph** $\mathbf{G} = (V, E_1, E_2, \dots, E_\tau)$ is defined as vertex set V with a list of edge sets E_1, \dots, E_τ over V , where τ is the lifetime of \mathbf{G} .

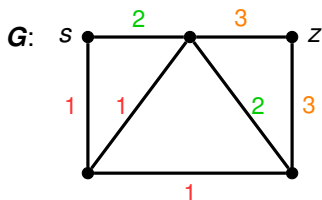
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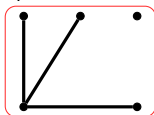


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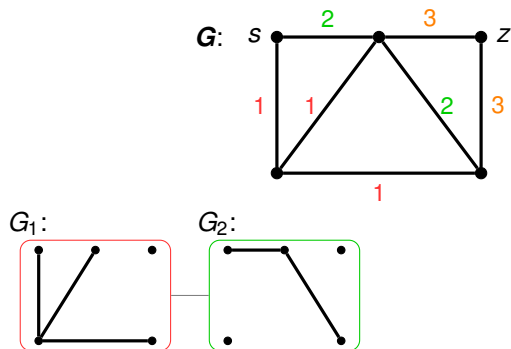


G_1 :



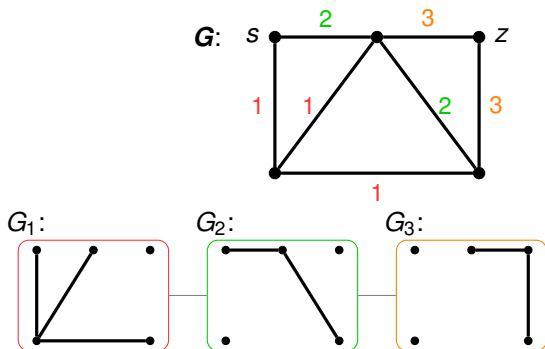
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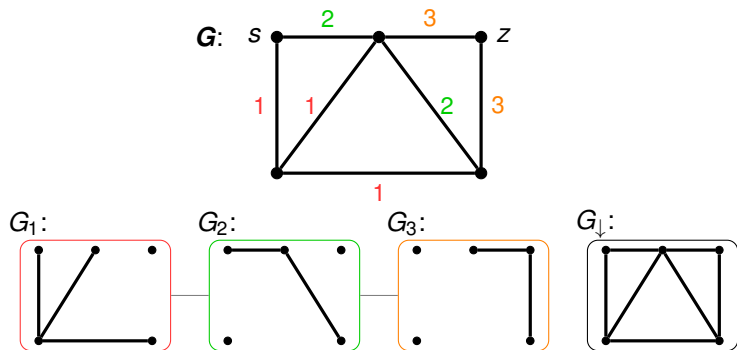
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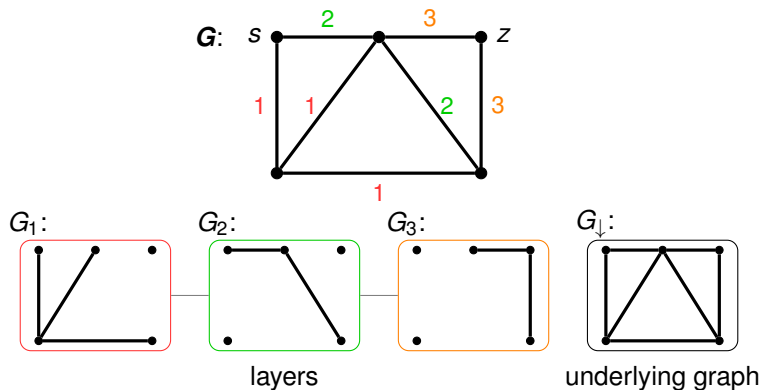
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Temporal Paths

A **strict** (s, z) -**path** of length ℓ in $\mathbf{G} = (V, E_1, \dots, E_\tau)$ is a list

$$P = ((\{s = v_0, v_1\}, t_1), \dots, (\{v_{\ell-1}, v_\ell = z\}, t_\ell)),$$

where $\{v_{i-1}, v_i\} \in E_{t_i}$ for all $i \in [\ell]$ and $v_i \neq v_j$ for all $i, j \in \{0, \dots, \ell\}$ with $i \neq j$ and for all $i \in [\ell - 1] : t_i < t_{i+1}$.

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Strict vs. Non-Strict Temporal Paths

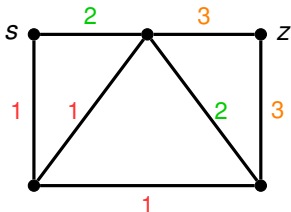
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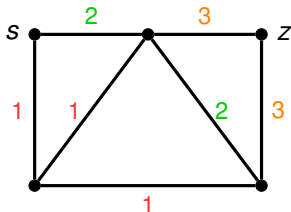
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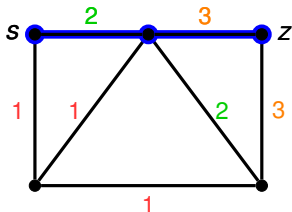
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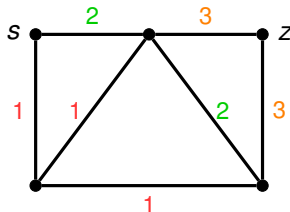
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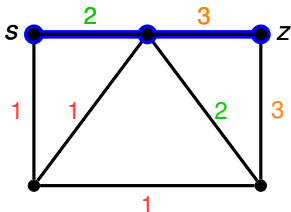
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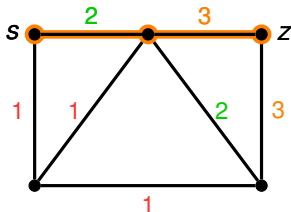
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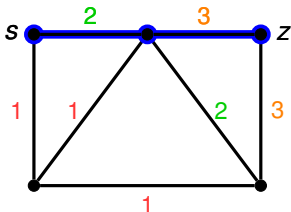
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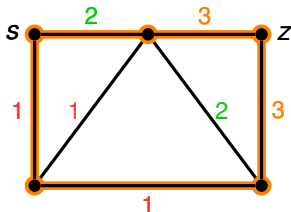
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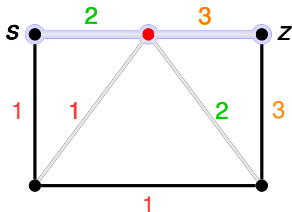
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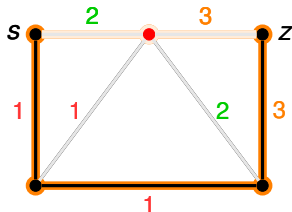
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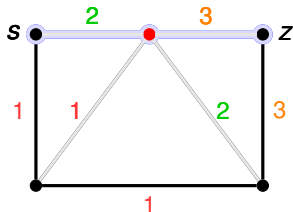
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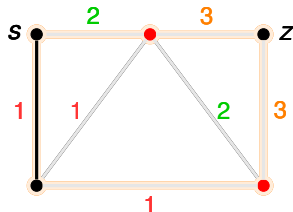
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Strict (s, z) -Separation

Input: A temporal graph $\mathbf{G} = (V, E_1, \dots, E_\tau)$ with two distinct vertices $s, z \in V$, and an integer k .

Question: Is there a subset $S \subseteq V \setminus \{s, z\}$ of size at most k such that there is no strict (s, z) -path in $\mathbf{G} - S$?

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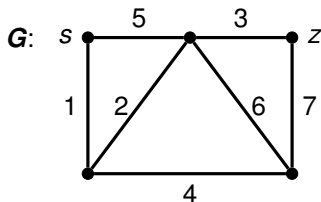
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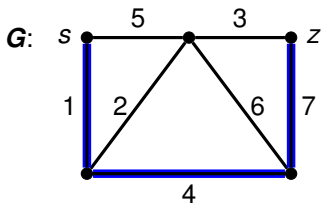
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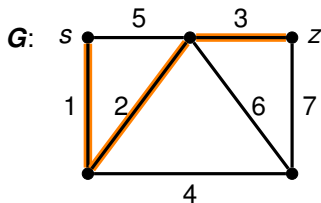
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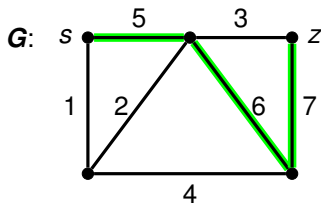
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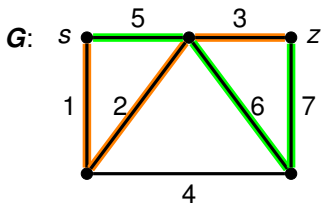
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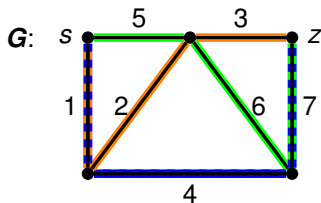
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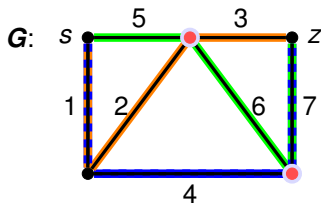
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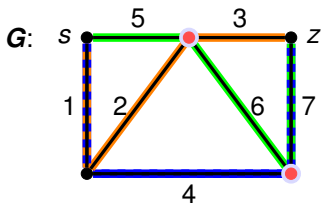
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The edge-deletion variant can be computed in polynomial-time.

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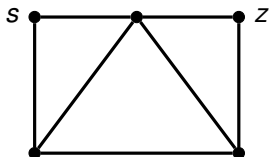
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- Menger's Theorem holds if the underlying graph **excludes** a fixed minor.

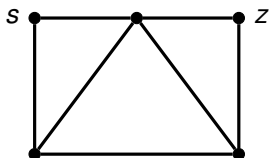
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This presentation is based on Fluschnik et al. [2018, WG] and Zschoche et al. [2018, MFCS]. (Both to appear, available on arXiv.)

Parameterized Tractability

- **FPT** (fixed-parameter tractable): Solvable in $f(k) \cdot n^{O(1)}$ time.

n : instance size

k : parameter

Parameterized Tractability

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Parameterized Hardness

- **W[1]-hard**: Presumably no FPT algorithm (XP algorithm possible).

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- **FPT** (fixed-parameter tractable): Solvable in $f(k) \cdot n^{O(1)}$ time.
- **XP**: Solvable in $n^{g(k)}$ time.

Parameterized Hardness

- **W[1]-hard**: Presumably no FPT algorithm (XP algorithm possible).
- **para-NP-hard**: NP-hard for constant k (no XP algorithm).

n : instance size

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Complexity of Finding Temporal Separators

Basic Results

Basic Results.

Parameter	(s, z)-Separation	
	Strict	Non-Strict
$2 \leq \tau \leq 4$	poly-time	para-NP-hard
$\tau \geq 5$	para-NP-hard	

Complexity of Finding Temporal Separators

Basic Results

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Parameter	(s, z)-Separation	
	Strict	Non-Strict
$2 \leq \tau \leq 4$	poly-time	para-NP-hard
$\tau \geq 5$	para-NP-hard	
k	W[1]-hard	W[1]-hard

Complexity of Finding Temporal Separators

Basic Results

Basic Results.

Parameter	(s, z)-Separation	
	Strict	Non-Strict
$2 \leq \tau \leq 4$	poly-time	para-NP-hard
$\tau \geq 5$	para-NP-hard	
k	W[1]-hard	W[1]-hard
$\tau + k$	FPT	<i>open</i>

Complexity of Finding Temporal Separators

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Complexity of Finding Temporal Separators

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Canonical next step: Restrict input graphs.

Complexity of Finding Temporal Separators

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Canonical next step: Restrict input graphs.

- Restrict each layer.

Complexity of Finding Temporal Separators

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$\tau + k$	FPT	open

Canonical next step: Restrict input graphs.

- Restrict each layer.
- Restrict the underlying graph.

Complexity of Finding Temporal Separators

Restricting each Layer

(Non-)Strict (s, z) -Separation with **restricted layers**.

Layer Restriction

| Complexity

Complexity of Finding Temporal Separators

Restricting each Layer

(Non-)Strict (s, z) -Separation with **restricted layers**.

Layer Restriction	Complexity
at most one edge	NP-hard and $W[1]$ -hard wrt. k

Complexity of Finding Temporal Separators

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at most one edge	NP-hard and $W[1]$ -hard wrt. k
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Complexity of Finding Temporal Separators

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Complexity of Finding Temporal Separators

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(Non-)Strict (s, z) -Separation with **restricted layers**.

Layer Restriction	Complexity
at most one edge	NP-hard and $W[1]$ -hard wrt. k
forest unit interval	para-NP-hard wrt. τ

Take away message:
Layer restrictions do not help much.

Complexity of Finding Temporal Separators

Restricting the Underlying Graph

(Non-)Strict (s, z) -Separation with **restricted underlying graph**.

Underlying Graph Restriction | Complexity

Complexity of Finding Temporal Separators

Restricting the Underlying Graph

(Non-)Strict (s, z) -Separation with **restricted underlying graph**.

Underlying Graph Restriction	Complexity
------------------------------	------------

bounded treewidth	poly-time (FPT wrt. $tw + \tau$)
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Complexity of Finding Temporal Separators

Restricting the Underlying Graph

(Non-)Strict (s, z) -Separation with **restricted underlying graph**.

Underlying Graph Restriction	Complexity
bounded treewidth	poly-time (FPT wrt. $tw + \tau$)
bounded vertex cover	poly-time (FPT)

Complexity of Finding Temporal Separators

Restricting the Underlying Graph

(Non-)Strict (s, z) -Separation with **restricted underlying graph**.

Underlying Graph Restriction	Complexity
bounded treewidth	poly-time (FPT wrt. $tw + \tau$)
bounded vertex cover	poly-time (FPT)
complete – $\{s, z\}$ bipartite line graph	para-NP-h wrt. τ / W[1]-h wrt. k

Complexity of Finding Temporal Separators

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(Non-)Strict (s, z) -Separation with **restricted underlying graph**.

Underlying Graph Restriction	Complexity
bounded treewidth	poly-time (FPT wrt. $tw + \tau$)
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planar	NP-hard (Strict: FPT wrt. τ)

Complexity of Finding Temporal Separators

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Complexity of Finding Temporal Separators

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(Non-)Strict (s, z) -Separation with **restricted underlying graph**.

Underlying Graph Restriction	Complexity
bounded treewidth	poly-time (FPT wrt. $tw + \tau$)
bounded vertex cover	poly-time (FPT)
complete – $\{s, z\}$ bipartite line graph	para-NP-h wrt. τ / W[1]-h wrt. k
planar	NP-hard (Strict: FPT wrt. τ)

Take away message:

Underlying graph restrictions help sometimes.

Complexity of Finding Temporal Separators

First Summary

We have seen so far:

Complexity of Finding Temporal Separators

First Summary

We have seen so far:

- Layer restrictions:

Complexity of Finding Temporal Separators

First Summary

We have seen so far:

- Layer restrictions: **do not seem to help.**

Complexity of Finding Temporal Separators

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Complexity of Finding Temporal Separators

First Summary

We have seen so far:

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- Underlying graph restrictions: **help only in few cases.**

Complexity of Finding Temporal Separators

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We have seen so far:

- Layer restrictions: **do not seem to help.**
- Underlying graph restrictions: **help only in few cases.**

Observation

All these restrictions are invariant under reordering of layers!

Complexity of Finding Temporal Separators

First Summary

We have seen so far:

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- Underlying graph restrictions: **help only in few cases.**

Observation

All these restrictions are invariant under reordering of layers!

Idea: Restrict “temporality” of the input graph.

Complexity of Finding Temporal Separators

Temporal Restrictions

Temporal graph classes with temporal aspects:

Restriction	(s, z)-Separation	
	Strict	Non-Strict

p -monotone

Definition (cf. Khodaverdian et al. [2016]; Casteigts et al. [2012])

$\mathbf{G} = (V, E_1, \dots, E_\tau)$ is **p -monotone** if there are $1 = i_1 < \dots < i_{p+1} = \tau$ such that for all $\ell \in [p]$ it holds that $E_j \subseteq E_{j+1}$ or $E_j \supseteq E_{j+1}$ for all $i_\ell \leq j < i_{\ell+1}$.

Complexity of Finding Temporal Separators

Temporal Restrictions

Temporal graph classes with temporal aspects:

Restriction	(s, z)-Separation	
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p -monotone	NP-h for $p \geq 1$	poly-time for $p = 1$, NP-h for $p \geq 2$

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Complexity of Finding Temporal Separators

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	Strict	Non-Strict
p -monotone	NP-h for $p \geq 1$	poly-time for $p = 1$, NP-h for $p \geq 2$

q -periodic

Definition (cf. Liu and Wu [2009]; Casteigts et al. [2012]; Flocchini et al. [2013])

$\mathbf{G} = (V, E_1, \dots, E_\tau)$ is **q -periodic** if $E_i = E_{i+q}$ for all $i \in [\tau - q]$. We call $r := \tau/q$ the number of periods.

Complexity of Finding Temporal Separators

Temporal Restrictions

Temporal graph classes with temporal aspects:

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Complexity of Finding Temporal Separators

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Complexity of Finding Temporal Separators

Temporal Restrictions

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Restriction	(s, z)-Separation	
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p -monotone	NP-h for $p \geq 1$	poly-time for $p = 1$, NP-h for $p \geq 2$

Definition (Kuhn et al. [2010])

$\mathbf{G} = (V, E_1, \dots, E_\tau)$ is **T -interval connected** if for every $t \in [\tau - T + 1]$ the graph $G = (V, \bigcap_{i=t}^{t+T-1} E_i)$ is connected.

T -interval connected

Complexity of Finding Temporal Separators

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T -interval connected	NP-h for $T \geq 1$	NP-h for $T \geq 1$
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Complexity of Finding Temporal Separators

Temporal Restrictions

Temporal graph classes with temporal aspects:

Restriction	(s, z)-Separation	
	Strict	Non-Strict
p -monotone	NP-h for $p \geq 1$	poly-time for $p = 1$, NP-h for $p \geq 2$

Definition

$\mathbf{G} = (V, E_1, \dots, E_\tau)$ is λ -**steady** if for all $t \in [\tau - 1]$ we have that $|E_t \Delta E_{t+1}| \leq \lambda$.

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-------------------------	---------------------	---------------------

λ -steady

Complexity of Finding Temporal Separators

Temporal Restrictions

Temporal graph classes with temporal aspects:

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Complexity of Finding Temporal Separators

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Complexity of Finding Temporal Separators

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Complexity of Finding Temporal Separators

Second Summary

We have seen so far:

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Complexity of Finding Temporal Separators

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Idea: Tailored restrictions that do not fit into the above categories.

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- Order-Preserving Temporal
Unit Interval Graphs.

Complexity of Finding Temporal Separators

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- Order-Preserving Temporal Unit Interval Graphs.
- Temporal Graph with bounded-sized Temporal Core.

(s, z) -Separation on Temporal Unit Interval Graphs

Order-Preserving Temporal Unit Interval Graph

Order-Preserving Temporal Unit Interval Graph

A temporal graph $\mathbf{G} = (V, E_1, \dots, E_\tau)$ is an **order-preserving temporal unit interval graph** if

(s, z) -Separation on Temporal Unit Interval Graphs

Order-Preserving Temporal Unit Interval Graph

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Order-Preserving Temporal Unit Interval Graph

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Order-Preserving Temporal Unit Interval Graph

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Recall: $<_V$ is compatible with a unit interval graph $G = (V, E)$ if $\{x, y\} \in E$ with $x <_V y$ implies $\{v \in V \mid x \leq_V v \leq_V y\}$ is a clique.

(s, z) -Separation on Temporal Unit Interval Graphs

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Motivation: Physical proximity networks in one-dimensional spaces.

(s, z) -Separation on Temporal Unit Interval Graphs

Poly-time Algo for Non-Strict (s, z) -Separation Order-Preserving Temporal Unit Interval Graphs



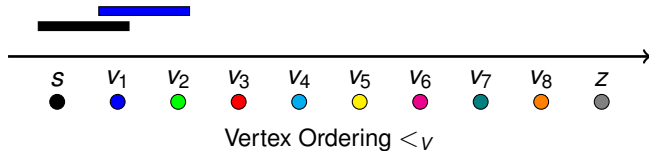
(s, z) -Separation on Temporal Unit Interval Graphs

Poly-time Algo for Non-Strict (s, z) -Separation Order-Preserving Temporal Unit Interval Graphs



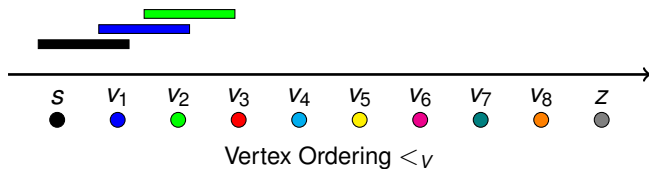
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Poly-time Algo for Non-Strict (s, z) -Separation Order-Preserving Temporal Unit Interval Graphs



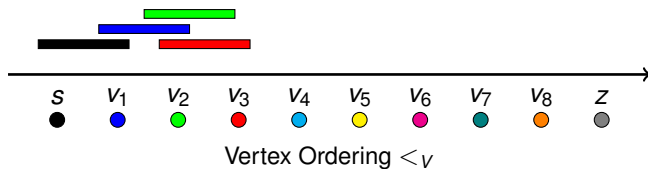
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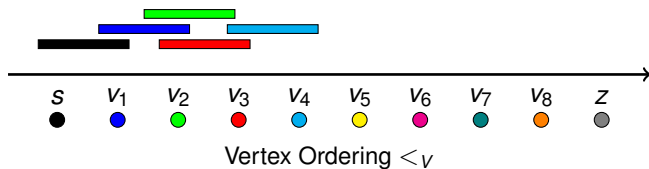
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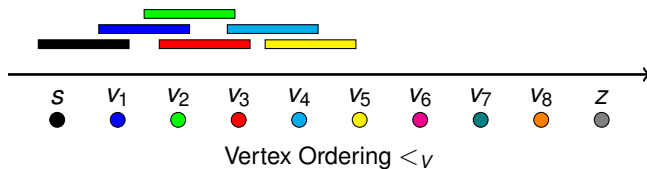
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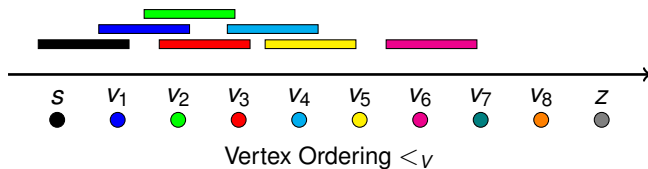
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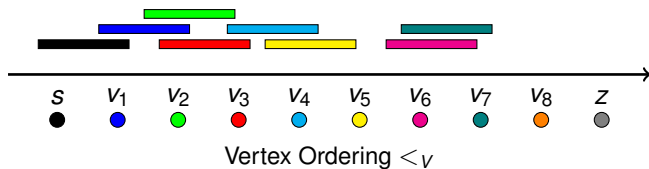
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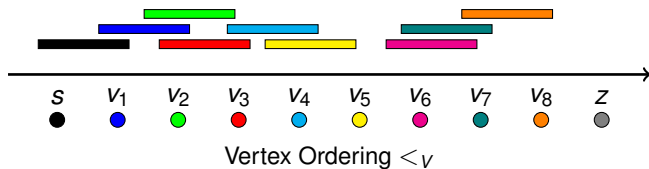
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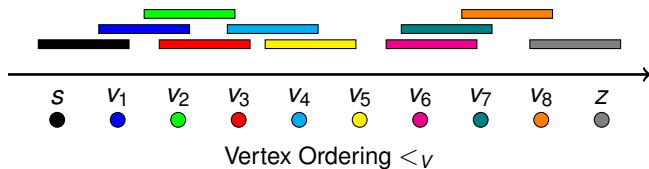
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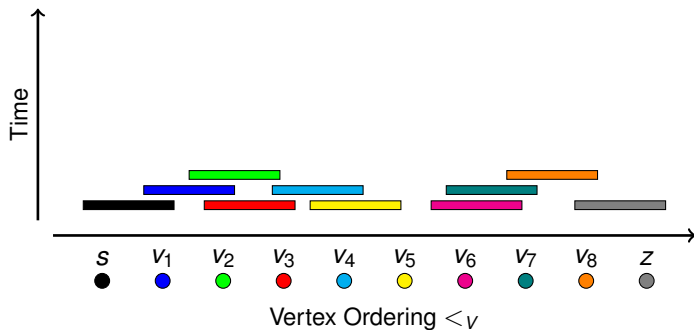
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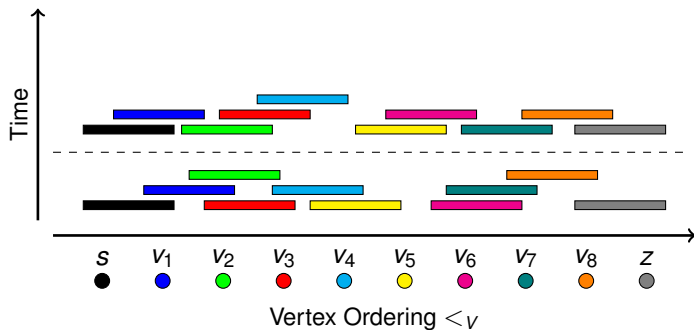
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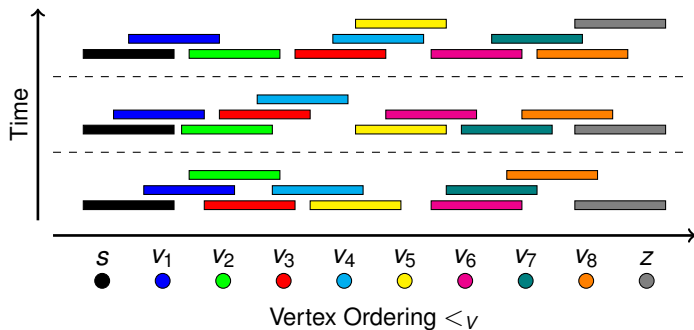
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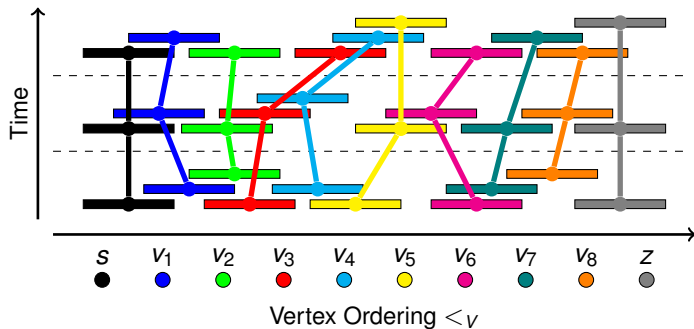
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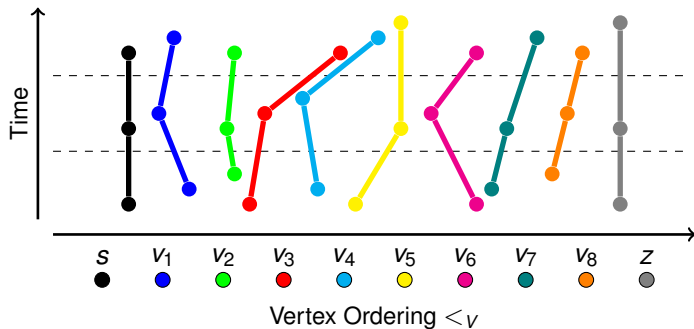
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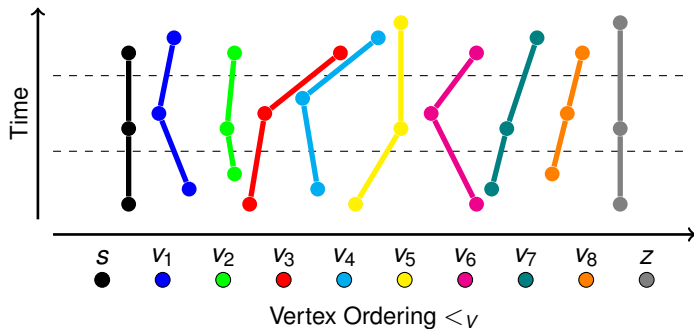
(s, z) -Separation on Temporal Unit Interval Graphs

Poly-time Algo for Non-Strict (s, z) -Separation Order-Preserving Temporal Unit Interval Graphs



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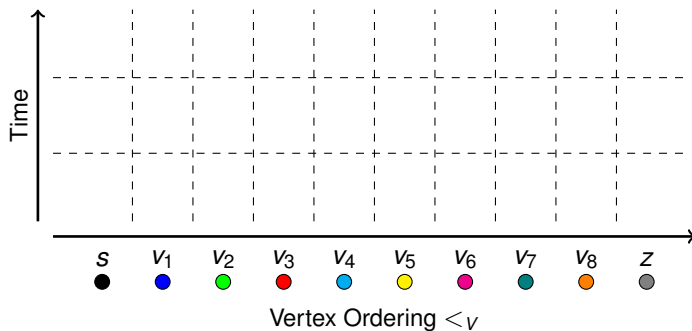


Observation

“Compatible” means these lines do not cross.

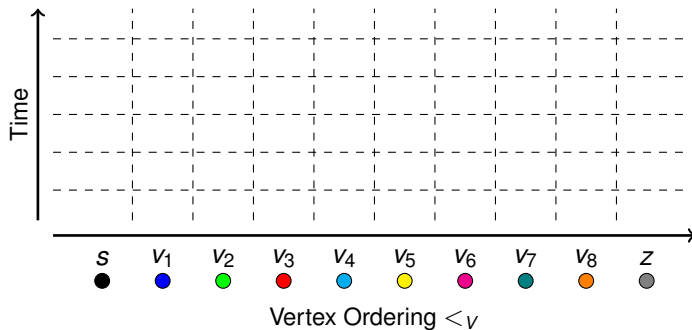
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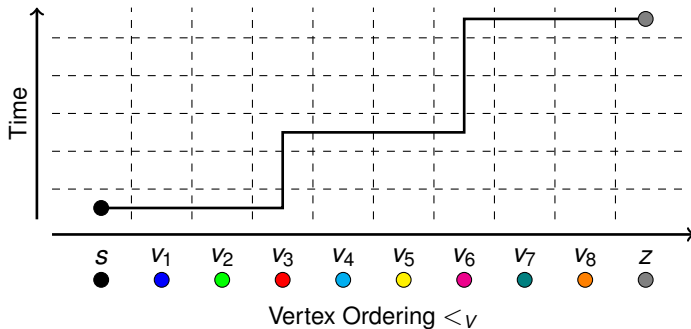
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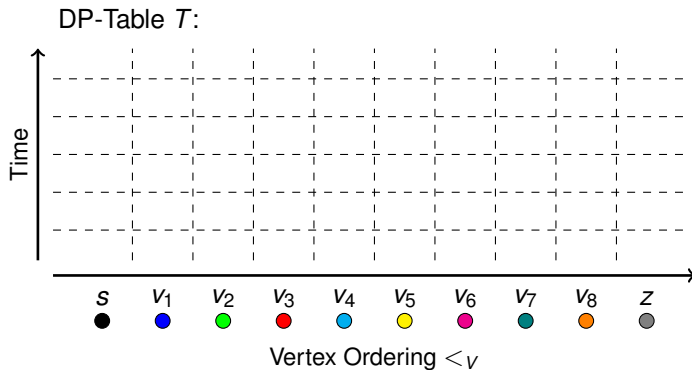


Observation

There are always temporal paths that follow the vertex ordering.

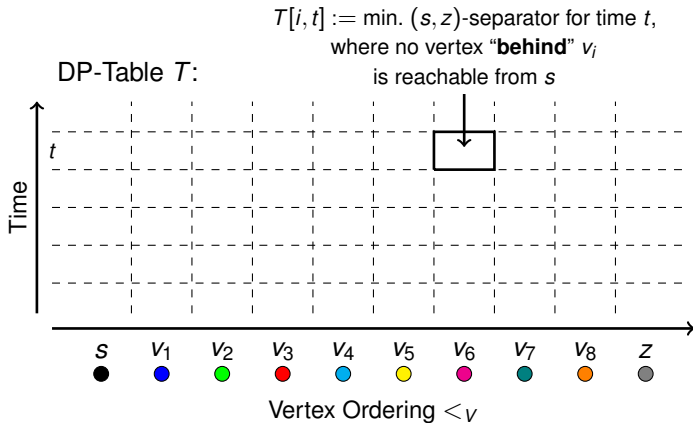
(s, z) -Separation on Temporal Unit Interval Graphs

Poly-time Algo for Non-Strict (s, z) -Separation Order-Preserving Temporal Unit Interval Graphs



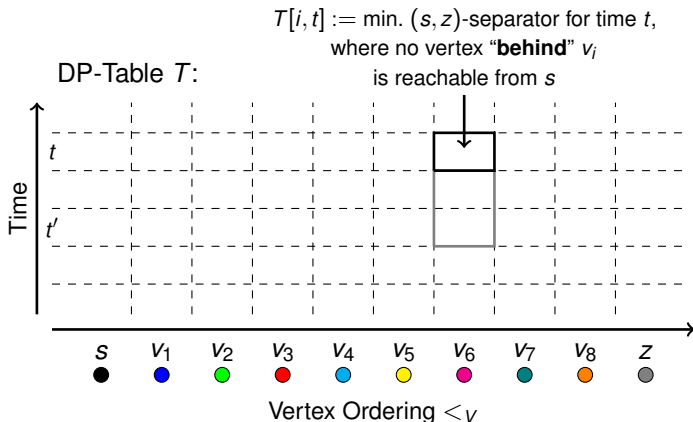
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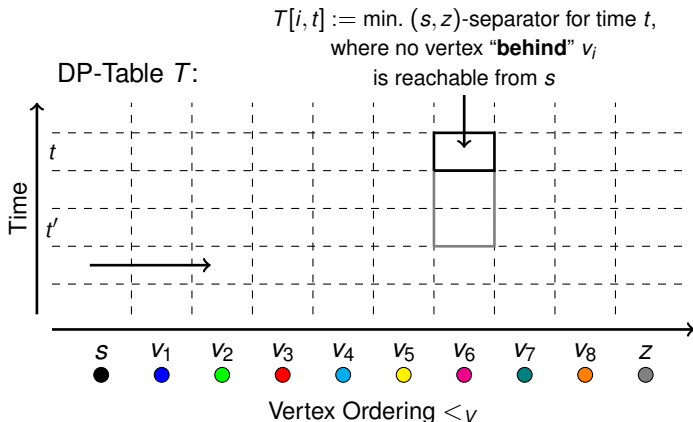
Poly-time Algo for Non-Strict (s, z) -Separation Order-Preserving Temporal Unit Interval Graphs



- Guess earliest time t' when v_i is reachable from s .

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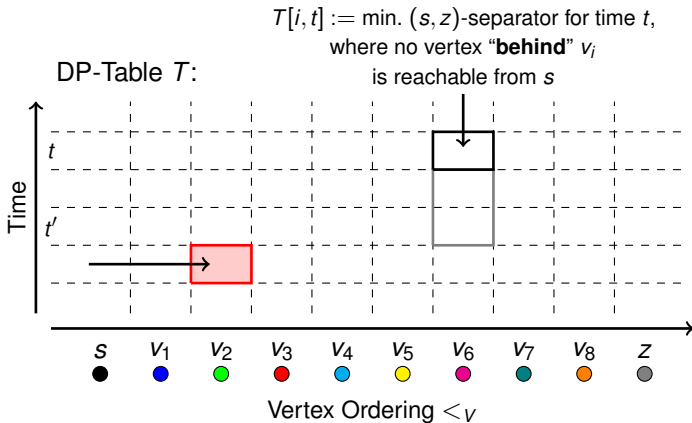
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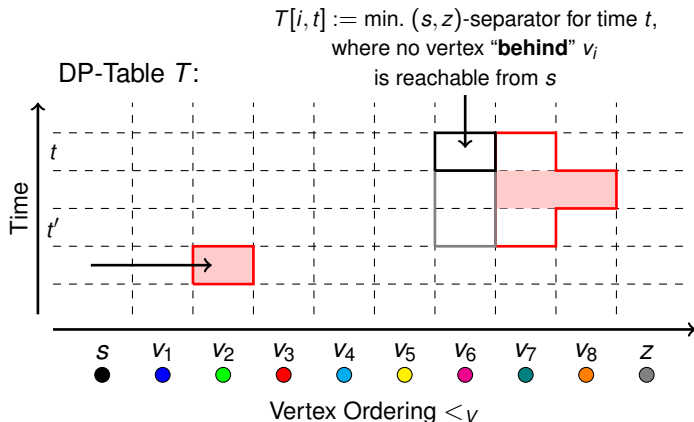
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(s, z) -Separation on Temporal Unit Interval Graphs

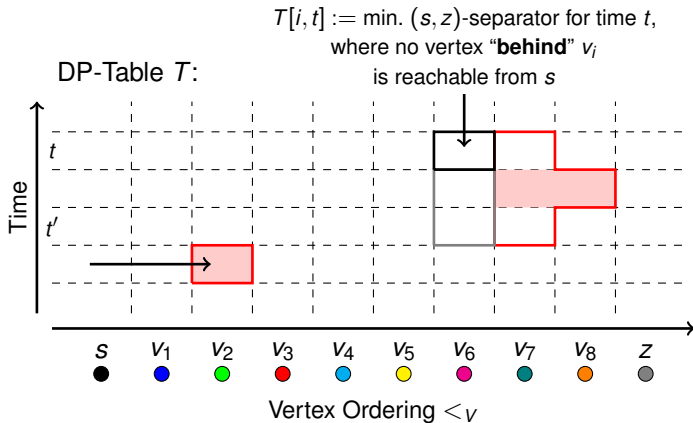
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- Guess earliest time t' when v_i is reachable from s .
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(s, z) -Separation on Temporal Unit Interval Graphs

Poly-time Algo for Non-Strict (s, z) -Separation Order-Preserving Temporal Unit Interval Graphs

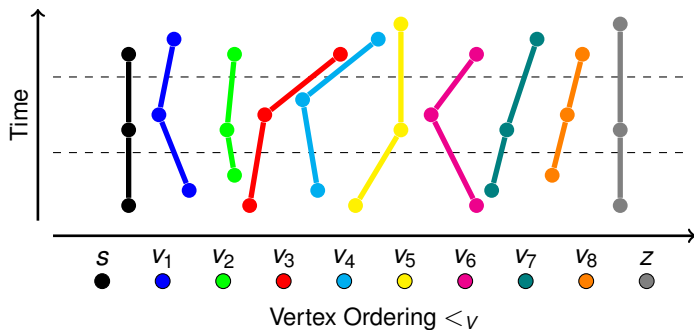


Theorem

Non-Strict (s, z) -Separation on order-preserving temporal unit interval graphs is poly-time solvable.

(s, z) -Separation on Temporal Unit Interval Graphs

Almost Order-Preserving Temporal Unit Interval Graphs

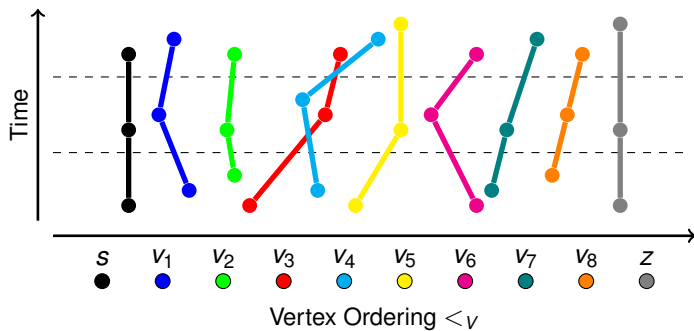


Observation

“Compatible” means these lines do not cross.

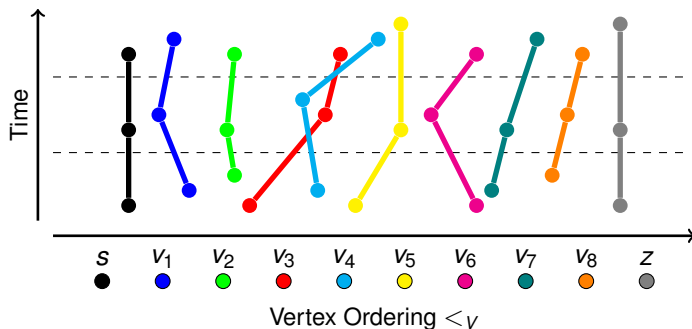
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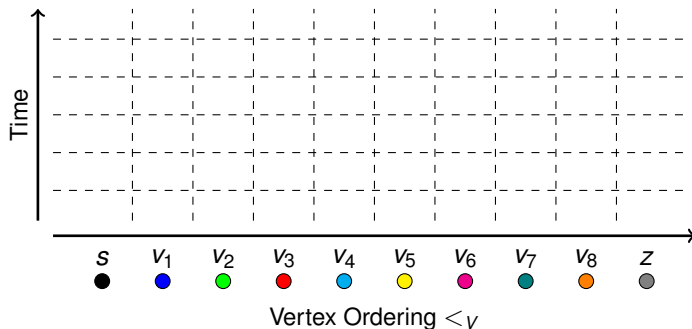
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- Idea: Bound number of crossings between consecutive time steps.
⇔ Vertex orderings have bounded **Kendall tau distance** κ .

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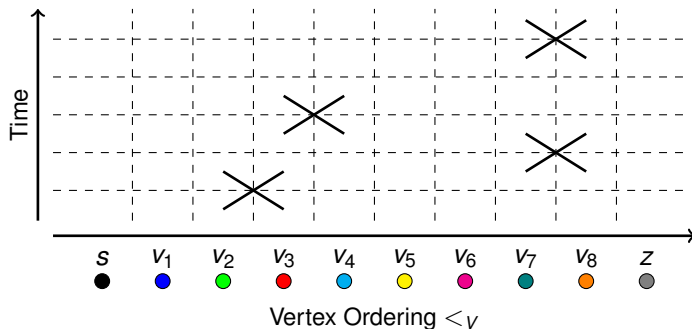
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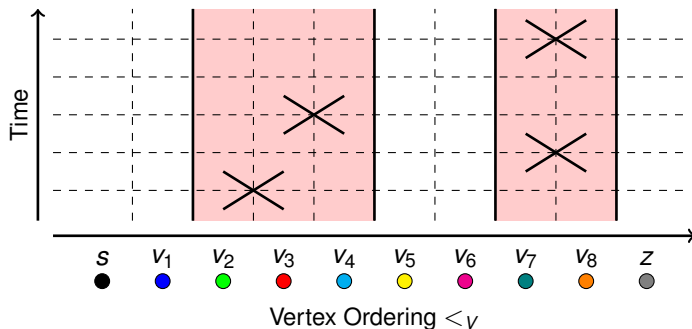
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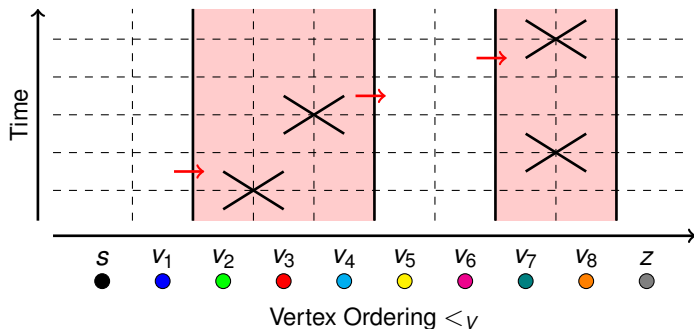
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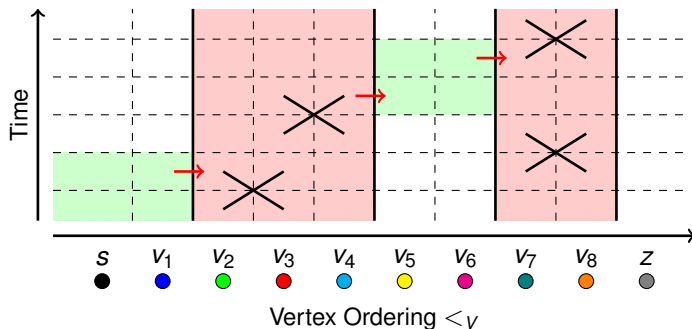
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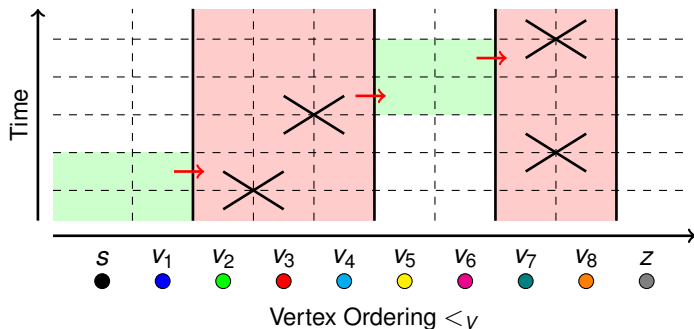
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Solve the rest with the poly-time algorithm.

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Almost Order-Preserving Temporal Unit Interval Graphs



- Idea: Bound number of crossings between consecutive time steps.
⇔ Vertex orderings have bounded **Kendall tau distance** κ .
- Brute-force the “regions” where crossings happen.
Solve the rest with the poly-time algorithm.
- Size of regions bounded by κ and the lifetime τ .

(s, z) -Separation on Temporal Unit Interval Graphs

Summary

Theorem

(Non-)Strict (s, z) -Separation on order-preserving temporal unit interval graphs is poly-time solvable.

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(Non-)Strict (s, z) -Separation on temporal unit interval graphs is FPT wrt. $(\kappa + \tau)$.

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Theorem

(Non-)Strict (s, z) -Separation on temporal unit interval graphs is para-NP-hard wrt. κ and para-NP-hard wrt. τ .

Temporal Core

The **temporal core** of $G = (V, E_1, \dots, E_\tau)$ is the vertex set

$$W = \{v \in V \mid \exists \{v, w\} \in (\bigcup_{i=1}^{\tau} E_i) \setminus (\bigcap_{i=1}^{\tau} E_i)\}.$$

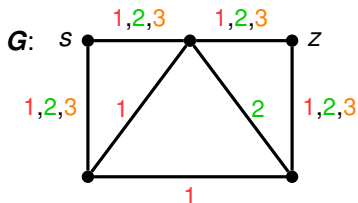
Temporal Core

Motivation and Definition

Temporal Core

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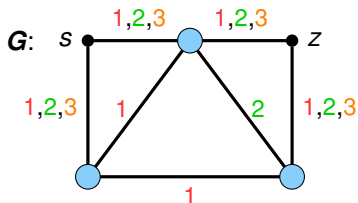
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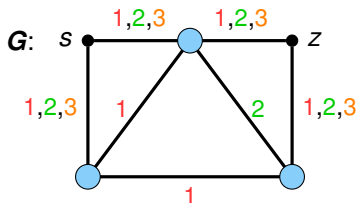
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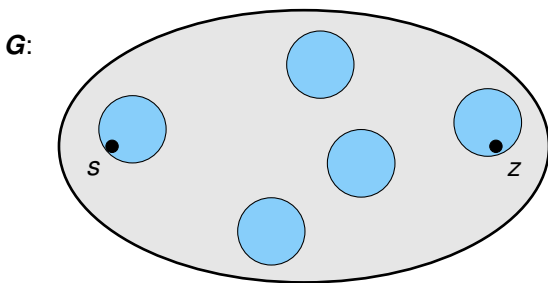


Recall: Strict (s, z) -Separation is NP-hard even if $W = \emptyset$.

Non-Strict (s, z) -Separation with small Temporal Cores

FPT Algorithm for “Size of the Temporal Core”

Given a temporal graph $\mathbf{G} = (V, E_1, \dots, E_\tau)$ with temporal core W :

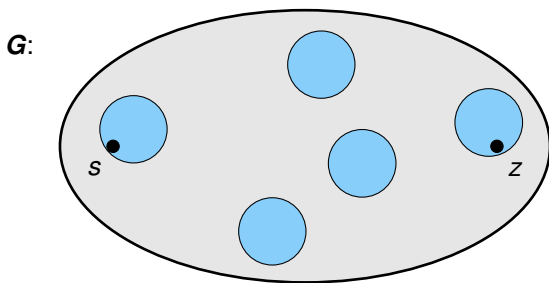


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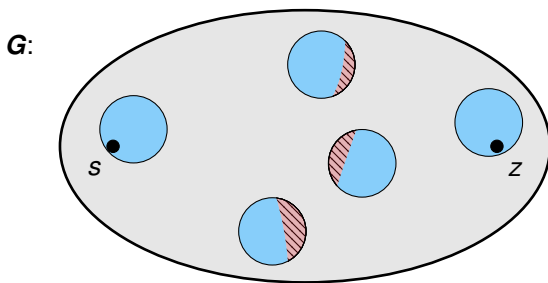


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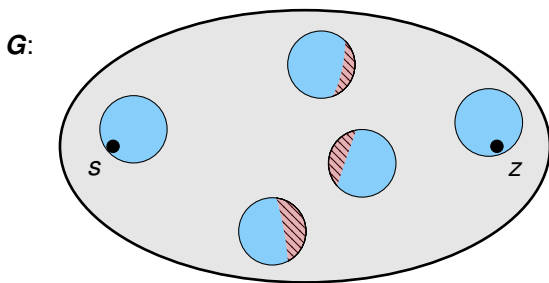


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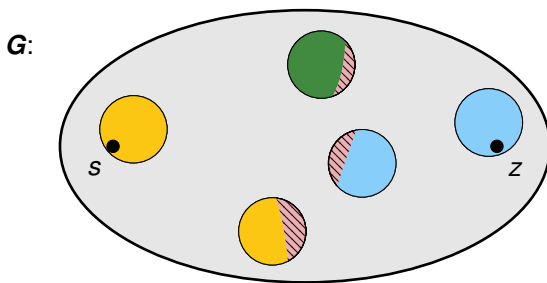


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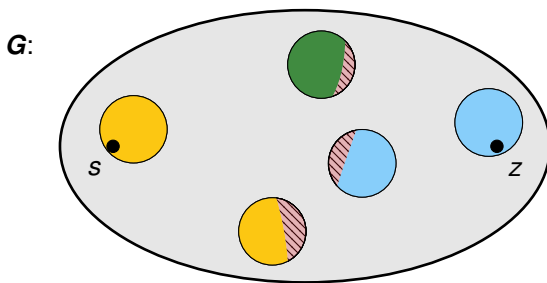


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- Use an algorithm for **Node Multiway Cut**.

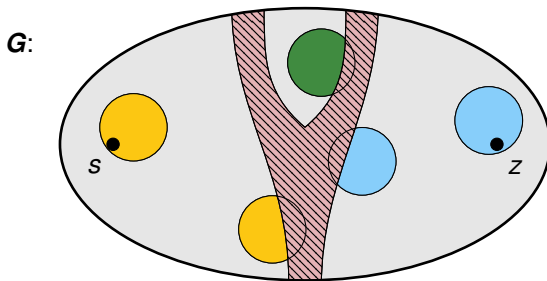


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Node Multiway Cut

Input: An undirected graph $G = (V, E)$, a set of terminal $T \subseteq V$, and an integer k .

Question: Is there a set $S \subseteq (V \setminus T)$ of size at most k such there is no (t_1, t_2) -path for every distinct $t_1, t_2 \in T$?

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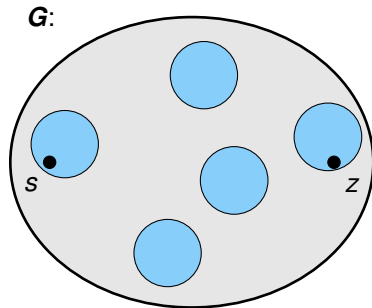
Theorem (Cygan et al. [2013], TOCT)

Node Multiway Cut can be solved in $2^{k-b} \cdot |V|^{O(1)}$ time,
where $b = \max_{x \in T} \min\{|S| \mid S \subseteq V \text{ is an } (x, T \setminus \{x\})\text{-separator}\}$.

Non-Strict (s, z) -Separation with small Temporal Cores

FPT Algorithm for “Size of the Temporal Core”

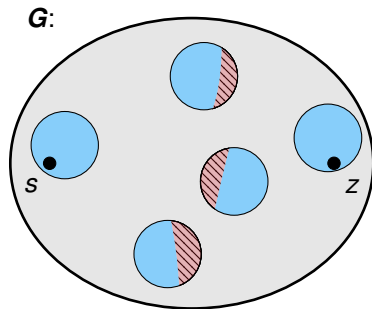
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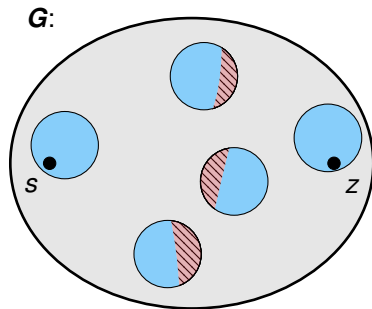
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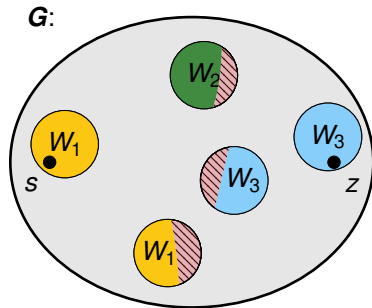
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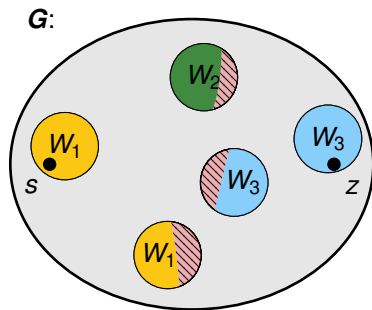
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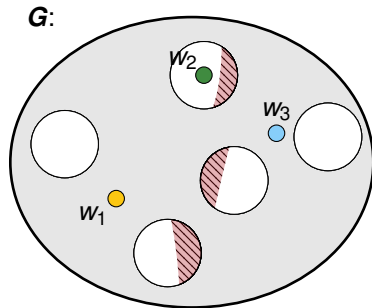
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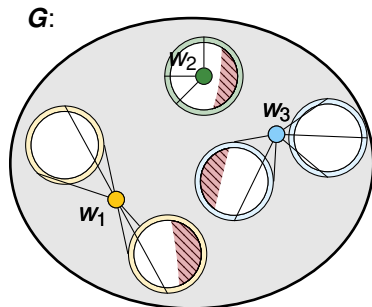


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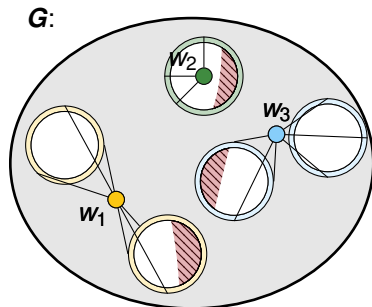
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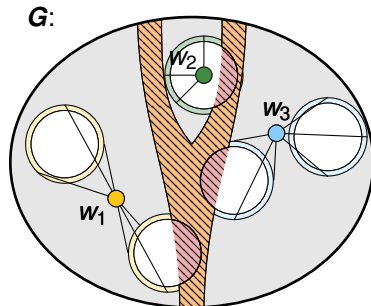
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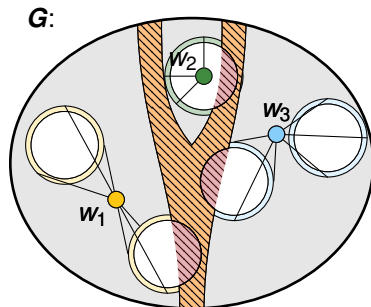
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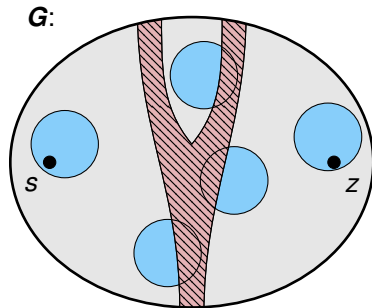
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Non-Strict (s, z) -Separation with small Temporal Cores

FPT Algorithm for “Size of the Temporal Core”

Theorem

Non-Strict (s, z) -Separation is FPT wrt. $|W|$.

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Non-Strict (s, z) -Separation is FPT wrt. $|W|$.

Given a temporal graph $\mathbf{G} = (V, E_1, \dots, E_\tau)$ with temporal core W :

- Guess which core vertices are part of the separator. **Ok!**
- Guess which core vertices need to be separated from each other. **Ok!**
- Use an algorithm for Node Multiway Cut.

Theorem (Cygan et al. [2013], TOCT)

Node Multiway Cut can be solved in $2^{k-b} \cdot |V|^{O(1)}$ time,
where $b = \max_{x \in T} \min\{|S| \mid S \subseteq V \text{ is an } (x, T \setminus \{x\})\text{-separator}\}$.

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Thank you!

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